### A proof-theoretic approach to ignorance

Marianna Girlando 1 Ekaterina Kubyshkina 2 Mattia Petrolo 3

<sup>1</sup>University of Amsterdam

<sup>2</sup>University of Milan

<sup>3</sup>Federal University of ABC

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#### Outline

- Introduction
- Representing ignorance
  - Ignorance whether
  - Ignorance of unknown truths
  - Disbelieving ignorance
- Labelled calculus labWUDI
- 4 Conclusions

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p := Paestum is in Italy.

Kp := I know that Paestum is in Italy.

 $\neg K \neg p := I$  am ignorant that Paestum is not in

Italy.

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- $I^{w}\phi$  is  $\nabla \phi$  defined by  $\neg K\phi \wedge \neg K\neg \phi$ .
- $\mathcal{M}, w \models I^w \phi$  iff there exists w' such that Rww' and  $\mathcal{M}, w' \models \phi$  and there exists w'' such that Rww'' and  $\mathcal{M}, w'' \models \neg \phi$ .

# System for ignorance whether

$$I^{\mathbf{w}}\phi = \nabla \phi$$
$$\triangle \phi = \neg \nabla \phi$$

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$$I^{w}\phi = \nabla\phi$$
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#### Definition (Fan & van Ditmarsch (2015))

- all instances of tautologies

- **5** From  $\phi$  and  $\phi \rightarrow \psi$  infer  $\psi$
- **o** From  $\phi$  infer  $\triangle \phi$
- **o** From  $\phi \leftrightarrow \psi$  infer  $\triangle \phi \leftrightarrow \triangle \psi$

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- $I^u \phi$  is • $\phi$  defined by  $\phi \wedge \neg K \phi$ .
- $\mathcal{M}, w \models I^u \phi$  iff  $\mathcal{M}, w \models \phi$  and there exists w' such that Rww' and  $\mathcal{M}, w' \models \neg \phi$

# System for ignorance of unknown truths

$$I^u \phi = \bullet \phi$$
$$\circ \phi = \neg \bullet \phi$$

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#### Definition (Steinsvold (2008))

- all propositional tautologies, substitution of equivalences, MP
- $\bigcirc \circ \top \leftrightarrow \top$

- **5** from  $\phi \to \psi$  infer  $(\circ \phi \land \phi) \to (\circ \psi \land \psi)$

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- $\mathcal{M}, w \models I^d \phi$  iff for all  $w' \neq w$  if Rww' then  $\mathcal{M}, w' \models \neg \phi$  and  $\mathcal{M}, w \models \phi$ .

# System for disbelieving ignorance

#### **Definition**

- Axioms:
  - (Taut) All instances of propositional tautologies
    - (11)  $I^d p \rightarrow p$
    - $(12) (I^d p \wedge I^d q) \rightarrow I^d (p \vee q)$
- Rules: modus ponens (MP), uniform substitution (US), and (IR) From  $\vdash \varphi \rightarrow \psi$ , infer  $\vdash \varphi \rightarrow (I^d \psi \rightarrow I^d \varphi)$

# System for disbelieving ignorance

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  - (11)  $I^d p \rightarrow p$
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- Rules: modus ponens (MP), uniform substitution (US), and (IR) From  $\vdash \varphi \rightarrow \psi$ , infer  $\vdash \varphi \rightarrow (I^d \psi \rightarrow I^d \varphi)$

The operators  $I^d$  and  $\square$  are not inter-definable in standard frames, such as K, T, S4, S5 etc.

## Examples

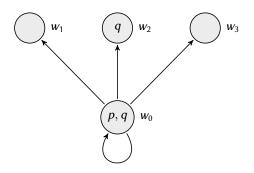


Figure: Model  $\mathcal{M}_1$ 

$$\mathcal{M}_1, w_0 \models I^d p, \ \mathcal{M}_1, w_0 \not\models I^d q, \ \mathcal{M}_1, w_0 \not\models I^d r$$

# **Examples**



Figure: Model  $\mathcal{M}_2$ 

$$\mathcal{M}_2, w_0 \models I^d \top$$

## Two-worlds property

An accessibility relation R satisfies the two-worlds property iff for all  $w \in W$ , there is a  $w' \in W$  such that wRw' and  $w \neq w'$ .

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•  $I^w$ ,  $I^u$ , and  $I^d$  represent different aspects of the polysemic notion of ignorance. From this perspective, these three types of ignorance should coexist in the same formal setting.

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We provide a labelled sequent calculus, and prove its soundness and completeness.

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# Our proposal

$$\phi ::= p \mid \bot \mid \phi \to \phi \mid \Box \phi \mid I^{\mathbf{w}} \phi \mid I^{\mathbf{u}} \phi \mid I^{\mathbf{d}} \phi$$

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## Ignorance models

 $\mathcal{M} = \langle W, R, v \rangle$ :

- $W \neq \emptyset$  set of possible worlds
- $R \subseteq W \times W$
- $v: Atm \rightarrow \mathcal{P}(W)$

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- $W \neq \emptyset$  set of possible worlds
- $R \subseteq W \times W$
- $v: Atm \rightarrow \mathcal{P}(W)$

*R* satisfies the two-worlds property:

for all  $x \in W$ , there is a  $y \in W$  such that xRy and  $x \neq y$ .

$$\frac{\Gamma \Rightarrow \Delta, x : \rho}{x : \rho, \Gamma \Rightarrow \Delta} \xrightarrow{\perp} \overline{x : \bot, \Gamma \Rightarrow \Delta}$$

$$\xrightarrow{\Gamma} \frac{\Gamma \Rightarrow \Delta, x : \phi \quad x : \psi, \Gamma \Rightarrow \Delta}{x : \phi \Rightarrow \psi, \Gamma \Rightarrow \Delta} \xrightarrow{\rightarrow_{R}} \frac{x : \phi, \Gamma \Rightarrow \Delta, x : \psi}{\Gamma \Rightarrow \Delta, x : \phi \Rightarrow \psi}$$

$$\xrightarrow{\Gamma} \frac{xRy, x : \Box \phi, y : \phi, \Gamma \Rightarrow \Delta}{xRy, x : \Box \phi, \Gamma \Rightarrow \Delta} \xrightarrow{\Gamma} \frac{xRy, \Gamma \Rightarrow \Delta, y : \phi}{\Gamma \Rightarrow \Delta, x : \Box \phi} *$$

$$\frac{\Gamma \Rightarrow \Delta, x : \rho}{x : \rho, \Gamma \Rightarrow \Delta} \xrightarrow{\perp} x : \bot, \Gamma \Rightarrow \Delta$$

$$\xrightarrow{\Gamma} \frac{\Delta, x : \phi \quad x : \psi, \Gamma \Rightarrow \Delta}{x : \phi \rightarrow \psi, \Gamma \Rightarrow \Delta} \xrightarrow{\rightarrow_{R}} \frac{x : \phi, \Gamma \Rightarrow \Delta, x : \psi}{\Gamma \Rightarrow \Delta, x : \phi \rightarrow \psi}$$

$$\xrightarrow{\Gamma} \frac{xRy, x : \Box \phi, y : \phi, \Gamma \Rightarrow \Delta}{xRy, x : \Box \phi, \Gamma \Rightarrow \Delta} \xrightarrow{\Gamma_{R}} \frac{xRy, \Gamma \Rightarrow \Delta, y : \phi}{\Gamma \Rightarrow \Delta, x : \Box \phi} *$$

$$\frac{xRy, xRz, y : \phi, \Gamma \Rightarrow \Delta, z : \phi}{x : I^{w}\phi, \Gamma \Rightarrow \Delta} * I_{R}^{w} \xrightarrow{x : \Box \neg \phi, \Gamma \Rightarrow \Delta} x : \Box \phi, \Gamma \Rightarrow \Delta$$

$$\Gamma \Rightarrow \Delta, x : I^{w}\phi$$

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$$\frac{\Gamma}{x:\rho,\Gamma\Rightarrow\Delta,x:\rho} \xrightarrow{\perp} x:\bot,\Gamma\Rightarrow\Delta$$

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$$\begin{array}{c} \operatorname{init} \overline{x:p,\Gamma\Rightarrow\Delta,x:p} & \stackrel{\perp}{x:\perp,\Gamma\Rightarrow\Delta} \\ \\ \rightarrow_{\mathsf{L}} \frac{\Gamma\Rightarrow\Delta,x:\phi \quad x:\psi,\Gamma\Rightarrow\Delta}{x:\phi\rightarrow\psi,\Gamma\Rightarrow\Delta} & \rightarrow_{\mathsf{R}} \frac{x:\phi,\Gamma\Rightarrow\Delta,x:\psi}{\Gamma\Rightarrow\Delta,x:\phi\rightarrow\psi} \\ \\ = \frac{xRy,x:\Box\phi,y:\phi,\Gamma\Rightarrow\Delta}{xRy,x:\Box\phi,\Gamma\Rightarrow\Delta} & \xrightarrow{\Box_{\mathsf{R}}} \frac{xRy,\Gamma\Rightarrow\Delta,y:\phi}{\Gamma\Rightarrow\Delta,x:\Box\phi} * \\ \\ I^{\mathsf{W}}_{\mathsf{L}} \frac{xRy,xRz,y:\phi,\Gamma\Rightarrow\Delta,z:\phi}{x:I^{\mathsf{W}}\phi,\Gamma\Rightarrow\Delta} * & I^{\mathsf{W}}_{\mathsf{R}} \frac{x:\Box\neg\phi,\Gamma\Rightarrow\Delta}{\Gamma\Rightarrow\Delta,x:I^{\mathsf{W}}\phi} \\ \\ I^{\mathsf{U}}_{\mathsf{L}} \frac{xRy,x:\phi,\Gamma\Rightarrow\Delta,y:\phi}{x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta} * & I^{\mathsf{U}}_{\mathsf{R}} \frac{\Gamma\Rightarrow\Delta,x:\phi}{\Gamma\Rightarrow\Delta,x:I^{\mathsf{U}}\phi} \\ \\ I^{\mathsf{U}}_{\mathsf{L}} \frac{x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta}{x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta} * & I^{\mathsf{U}}_{\mathsf{R}} \frac{\Gamma\Rightarrow\Delta,x:\phi}{r\Rightarrow\Delta,x:I^{\mathsf{U}}\phi} \\ \\ I^{\mathsf{U}}_{\mathsf{L}} \frac{x:I^{\mathsf{U}}\phi,x:\phi,\Gamma\Rightarrow\Delta}{x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta} * & I^{\mathsf{U}}_{\mathsf{R}} \frac{xRy,x\neq y,x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta}{xRy,x\neq y,x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta} \\ \\ I^{\mathsf{U}}_{\mathsf{L}} \frac{x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta}{x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta} * & I^{\mathsf{U}}_{\mathsf{L}} \frac{xRy,x\neq y,x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta,y:\phi}{xRy,x\neq y,x:I^{\mathsf{U}}\phi,\Gamma\Rightarrow\Delta} * \\ I^{\mathsf{U}}_{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}} \frac{x}{x} \xrightarrow{\mathsf{L}} \xrightarrow{\mathsf{L}$$

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init 
$$\frac{1}{x:p,\Gamma\Rightarrow\Delta,x:p}$$
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# Derivation example

```
 \frac{\int \limits_{\mathbb{R}^{1}} \frac{x : I^{w}p, x : I^{d}p, x : p \Rightarrow x : p}{I^{u}_{\mathbb{R}}} \frac{\int \limits_{\mathbb{R}^{1}} \frac{x Ry, xRz, y : p, x : \square p, z : p, x : I^{w}p, x : I^{d}p \Rightarrow z : p}{x x Ry, xRz, y : p, x : \square p, x : I^{w}p, x : I^{d}p \Rightarrow z : p} \frac{\int \limits_{\mathbb{R}^{u}} \frac{x Ry, xRz, y : p, x : \square p, x : I^{w}p, x : I^{d}p \Rightarrow z : p}{x : \square p, x : I^{w}p, x : I^{d}p \Rightarrow z : p}}{x : I^{w}p, x : I^{d}p \Rightarrow x : I^{u}p} \frac{x : I^{w}p, x : I^{d}p \Rightarrow x : I^{u}p}{\Rightarrow x : I^{w}p \wedge I^{d}p \Rightarrow x : I^{u}p}
```

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*If there is a derivation of*  $\Rightarrow$  *x* :  $\phi$ ,  $\phi$  *is valid.* 

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$${}_{2w}\frac{\textit{xRy}, \textit{x} \neq \textit{y}, \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta} *$$

Do not apply 2w to  $\Gamma \Rightarrow \Delta$  if for any x in  $\Gamma \Rightarrow \Delta$  either:

- (a) xRy and  $x \neq y$  are in  $\Gamma$  for some y; or
- (b) zRx and  $z \neq x$  are in  $\Gamma$ , for some z such that For(z) = For(x).

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#### Theorem (Termination)

Root-first proof search for a sequent  $\Rightarrow x : \phi$  comes to an end in a finite number of steps.

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Proof. We construct a countermodel  $\mathcal{M}^{\mathcal{B}} = \langle \mathcal{W}^{\mathcal{B}}, \mathcal{R}^{\mathcal{B}}, \mathcal{V}^{\mathcal{B}} \rangle$  from a branch of a failed proof search tree:

- $\bullet \ \mathcal{W}^{\mathcal{B}} = \{x \mid x \in \Gamma \cup \Delta\};$
- $\mathcal{R}^{\mathcal{B}} = \{(x,y) \mid xRy \in \Gamma\};$
- $\mathcal{V}^{\mathcal{B}}(p) = \{x \in \mathcal{W}^{\mathcal{B}} \mid x : p \in \downarrow \Gamma\}.$

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- $\mathcal{R}^{\mathcal{B}} = \{(x, y) \mid xRy \in \Gamma\};$
- $V^{\mathcal{B}}(p) = \{x \in \mathcal{W}^{\mathcal{B}} \mid x : p \in \downarrow \Gamma\}.$

 $\mathcal{M}^{\mathcal{B}}$  might not satisfy the two-worlds condition!

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Proof. We construct a countermodel  $\mathcal{M}^{\mathcal{B}} = \langle \mathcal{W}^{\mathcal{B}}, \mathcal{R}^{\mathcal{B}}, \mathcal{V}^{\mathcal{B}} \rangle$  from a branch of a failed proof search tree:

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 $\mathcal{M}^{\mathcal{B}}$  might not satisfy the two-worlds condition!

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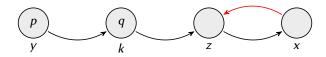
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## Example



$$W = \{x, y, z, k\}; R = \{(x, y), (y, z), (z, k), (k, z)\}; v(p) = \{x\}.$$

## Outline

- Introduction
- Representing ignorance
  - Ignorance whether
  - Ignorance of unknown truths
  - Disbelieving ignorance
- Labelled calculus labWUDI
- Conclusions

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Questions?